

#### Performing reliable and reproducible frequency response measurements on power transformers

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#### Abstract

The Sweep Frequency Response Analysis (SFRA) has become a standard method to assess the mechanical and electrical integrity of the power transformer's active part. It provides a very high sensitivity to evaluate possible damages after transportation or for troubleshooting after a specific event such as a near failure with high short-circuit forces. However, users often struggle to reach a high reproducibility which is essential for a reliable condition assessment. Deviations, caused by reproducibility issues, can lead to a misinterpretation, unnecessary inspections or cost-intensive maintenance activities. This paper focuses on best practices in order to perform highly repeatable and reproducible SFRA measurements.

## 1 Introduction

The Sweep Frequency Response Analysis (SFRA) method was introduced to verify the integrity of the active part of a power transformer. After manufacturing, power transformers are transported on-site, often over long distances using different types of transportation such as ship, train or truck. Both during transportation and loading from one vehicle to another, the transformer might be exposed to mechanical shocks. Such shocks can also be caused by earthquakes or mechanical impacts due to short-circuit forces after a failure. All these impacts can lead to a deformation or partial movement in the active part. Common diagnostic measurements such as transformer turns ratio including exciting currents, short-circuit impedance at nominal frequency as well as frequency response of stray losses (FRSL) may have disadvantages regarding to their sensitivity to detect and prove mechanical deformations. For example, a buckling of a winding does not typically influence ratio or insulation resistance measurements and is hard to detect in a change of capacitance. Compared to them the SFRA is the most sensitive method for reliable core and winding assessment [1]. This paper shows several best practices how to perform SFRA measurements in order to ensure highly repeatable and reproducible test results.

### 2 Basics of the SFRA method

The SFRA method comprises a highly repeatable and reproducible frequency response measurement on a power transformer and the subsequent comparison with an existing fingerprint, also called a reference measurement [3], [4]. In principle three methods are commonly used to assess the measured SFRA traces:

- Time-based (current SFRA results will be compared to previous results of the same unit)
- Construction-based (SFRA of one transformer will be compared to another of the same design)
- Phase-based (SFRA results of one phase will be compared to the other traces of the same unit)

The preferred method is the time-based comparison. However, the fingerprint or base-line measurement is in the majority of the cases not available. Nevertheless, by a simple comparison of the SFRA plots of the phases or by a type-based comparison, a successful assessment of the results can be achieved. Even if a fingerprint of the transformer is available, the experience has demonstrated that the comparison has to be carried out carefully because in some cases the deviations observed are not related to deformations, but to measurements under different conditions or due to measurement mistakes [8]. For overcoming these misleading factors, the comprehensive time-based comparison concept is proposed in this paper.

#### 2.1 Frequency response measurement

The active part of a power transformer, consisting of the winding, core, insulation and connecting leads, forms a complex electrical network as indicated in Figure 1. Such a network has unique characteristics which can be visualized by the frequency response: A frequency-variable sinusoidal low-voltage signal of, for example 10 V, is applied to one terminal and the response (U2) is measured at another terminal (Figure 2). In order to measure the amplitude, phase and frequency of the injected signal, a reference measurement channel (U1) is connected to the same injection point as the source [2]. The frequency response consists of amplitude, ratio and phase difference between both terminals.

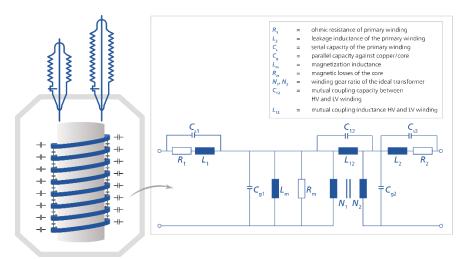


Figure 1: Simplified R-L-C equivalent circuit of a power transformer

The frequency response can be measured in different ways in order to gather more information for a sophisticated assessment. The most common approach is the open-circuit measurement. Thereby, the frequency response is measured between two terminals of the same voltage level, leaving all other terminals open. When shorting the terminals of the other voltage level (for example, the low-voltage winding when measuring the high-voltage windings), a short-circuit measurement is performed. A capacitive inter-winding measurement describes a test between two windings on the same core limb (for example the high- and low-voltage winding), while all other terminals are open. An inductive inter-winding measurement is also performed between two windings on the same core limb, whereas the measurement clamps are mounted on each winding terminal and the other end of the winding is connected to ground.

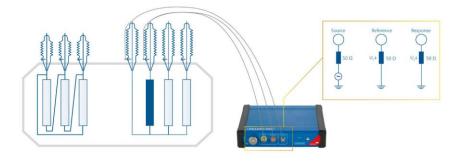


Figure 2: Typical setup of a sweep frequency response analysis

# 2.2 Analysis methods for SFRA measurements

Depending on their main influences, different failure modes will be revealed stronger in different frequency ranges. As an example, core phenomena will influence the low-frequency region whereas connection issues in the very high-frequency range above 1MHz [1]. Experience shows that setup issues, such as not following the shortest braid concept can influence the frequency response even at 500kHz. However, it is difficult to provide a general table with shows the relation between the frequency range and transformer characteristics as there are too many factors which are influencing the frequency range (e.g. MVA rating, winding type, voltage level, etc.). Basic references can be found within the CIGRE brochure. Different analysis tools can be used based on mathematical indices [5] or characteristic changes within the measured curves [6].

For every analysis, a fingerprint or baseline measurement is necessary. If available, a comparison should always be made to a previous measurement of the same transformer using the same configuration [7], a so called time-based comparison. Such a reference measurement can originate, for example, from commissioning tests or in-depth testing on site. Alternatively, if no reference measurement from this transformer is available, the frequency response can be compared with a sister asset. Sister assets typically have a very similar, but not identical, frequency response as shown in Figure 3. Therefore, small deviations are acceptable and do not necessarily indicate a problem.

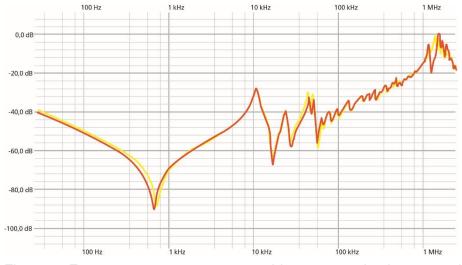


Figure 3: Frequency response measured in an open-circuit test on sister transformers (200 MVA, 230 kV interleaved disk winding)

In cases where even no trace of a sister asset is available, phase-to-phase comparisons might be applied. A good comparison is only possible for a symmetrical design, which is not exactly given for common designs. Even larger deviations can be caused by constructive differences between phases. Phase-to-phase comparisons, therefore, require the greatest amount of experience. Typically, the centre phase includes the most deviation, whereas the other two phases overlay with reasonable similarity. The main deviations between the centre phase and outer phases are expected at lower frequencies, which are mainly affected by the core due to the different flux paths.



Figure 4: Comparison of the frequency response traces measured on three phases of the same transformer (200 MVA, 230 kV interleaved disk winding)

### 3 Importance of the connection technique

The SFRA is a very sensitive method used to detect even the smallest changes within the electrical network of a power transformer. The advantage of being highly sensitive can sometimes be a disadvantage in terms of repeatability and noise sensitivity. Therefore, the connection technique is essential to achieve a high degree of reproducibility, especially in the high-frequency range above 500 kHz [1], [9].

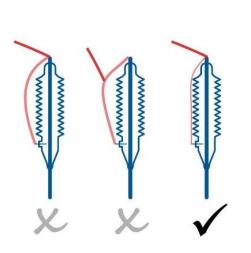


Figure 5: Schematic of the recommended setup according to IEC 60076-18



Figure 6: Example of shortest-braid connection concept - measurement cables (black) are connected to the bushing terminal and the grounding braid to the terminal and bushing flange

The IEC 60076-18 standard describes the recommended procedure for a proper and reproducible measurement setup in detail (Figure 5). It is recommended to use double-shielded coaxial cables which are connected to the bushing terminal. From here, a connection to the flange or tank should be installed on a low inductive ground, preferably using a flat, wide aluminum braid instead of a simple wire. As explained in [9], braids have a large surface, a low inductance, and the mesh reduces the considerable skin-effect above 80 kHz. As a consequence, the braid structure provides a better conductivity for high frequencies, resulting in a more efficient noise suppression towards ground compared to the use of simple wires.

The length of the ground connection influences the frequency response. To achieve a high reproducibility, it is suggested to use the shortest possible length by pulling the braid tightly along the body of the bushing as shown in Figure 6.

Besides the connection technique itself, it is important to establish a proper electrical contact between the terminal respectively flange and the measurement clamp used. Cleaning the terminal and removing lacquer layers help to reduce the contact resistance. Modern SFRA devices provide a ground-loop check to ensure proper connections with a low contact resistance to ground.

### 4 Influencing factors of the frequency response

As discussed above, it is essential for a comparative method such as SFRA, to provide the highest confidence in excluding influencing factors related to the measurement setup or external factors which will be described within the following chapter. For the sake of completeness, it is worth to mention that for the described usecases the OMICRON FRANEO 800 SFRA test system was used and the end-to-end open circuit measurement was conducted on various assets.

### 4.1 Factors on the measurement setup

### Shorting and grounding of tertiary windings and separate neutral terminals

The measurement type "open-circuit" or "short-circuit" defines whether the terminals of the opposite voltage level have to be short-circuited or not. That means, when measuring the high voltage side, it defines whether to short circuit the low voltage terminals or not.

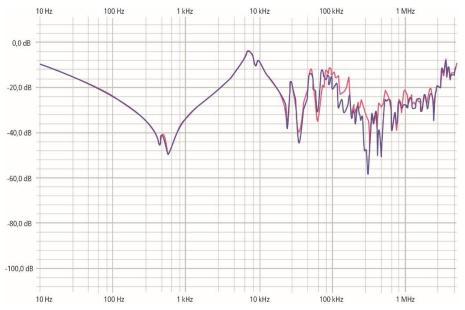


Figure 7: Influence of grounded (blue) and ungrounded (red) tertiary on measured LV opencircuit curves

The measurement type does not provide information on how to handle separate neutral terminals or tertiary windings which significantly influence the measured frequency response. This includes floating, closed or grounded tertiary windings. Figure 7 shows the deviations between two open-circuit measurements made on the low-voltage windings with grounded and ungrounded tertiary winding. Various deviations, especially within the area of mutual coupling (interaction of the windings) on the measured frequency response can be observed. In general the frequency response for the magnetization inductance and parallel capacitance remain unaffected. Therefore, it is suggested to leave all other terminals open and ungrounded as recommended in the IEEE Standard C57.149 [3].

## **Measurement direction**

The measurement direction, meaning in the case of star-connected power transformers from phase to neutral or neutral to phase, significantly influences the high-frequency behavior as shown, for example, in Figure 8.

If not specified differently, it is suggested to have the source and reference lead connected to the phase terminal and the response lead to the neutral terminal[3], [4].

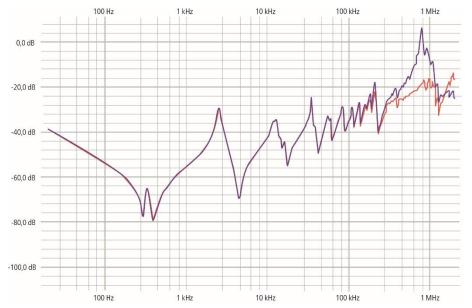


Figure 8: Influence measuring direction, source to phase (blue) vs. source to neutral (red)

#### **Output voltage**

In the low-frequency range, the frequency response is dominated by the core magnetization inductance and, therefore, depends on the output voltage as shown in Figure 9. The residual curve is not affected by the output voltage as the transformer windings can be considered as a linear system, which is, in principle, unaffected by the output voltage.

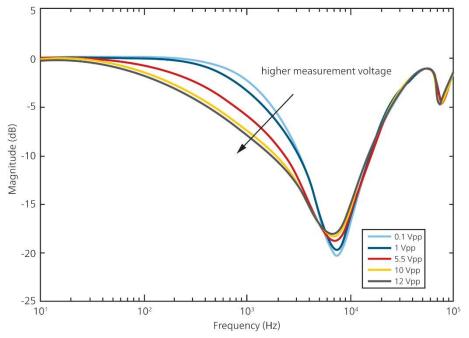


Figure 9: Effect of the selected output voltages; influence of different output voltages on magnetization inductance Lm

#### Grounding and measurement leads

Different procedures to connect the measurement and grounding leads are explained in IEC 60076-18 [4]. The most common way is to use specially-designed clamps connecting the double-shielded BNC-cable to the phase terminal and to apply a braid respectively wire for grounding the shield between the clamp and the bushing flange. As described in section 3, using a braid instead of a wire will significantly reduce the noise influence, especially around mains frequency. Furthermore, the length of the ground lead is essential for the low-frequency region as shown in Figure 10. When using leads with a fixed length, the position of the lead influences the frequency response. Therefore, the concept of adapting the ground lead in order to ensure the shortest path to ground, provides the highest degree of reproducibility.



Figure 10: Influence of different connection techniques, lowest noise influence and highest repeatability by using a ground braid in the shortest path concept (blue), wire connection (green) and ground braid with a bigger loop (red)

#### Tap changer position and bushings

In accordance with the applicable standards, SFRA tests must be performed with the same transformer configuration, including bushings or tap changer position. Sometimes test bushings are used during factory acceptance tests and the final bushings are mounted on-site. When comparing the frequency response measured in the factory with the one measured on-site, deviations will occur most probably in the high-frequency range. Changing the tap changer position will cause continuous changes of the curve shape over a wide frequency range, as shown in Figure 11. It is suggested to perform measurements for each relevant phase on the lowest, highest and middle position of the tap changer, while switching continuously from the higher to lower position [3], [4].

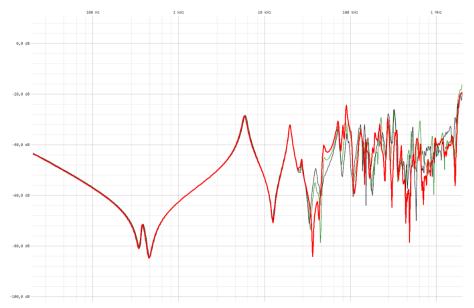


Figure 11: Influence of tap changer position (tap 1: red, tap 2: green, tap 3: black) on the frequency response of a power transformer

### Contact between bushing terminal and ground lead

One of the most typical connection errors is an unwanted contact of the ground lead with the bushing terminal. Such an error influences the frequency response mainly on the higher frequencies as shown in Figure 12. It is recommended to use an insulating cover for braids in order to avoid this short circuit.

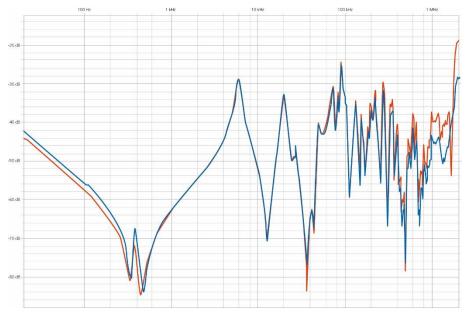


Figure 12: Frequency response measured on HV side in an open-circuit test; proper connected (red) and short-circuit between terminal and ground at the reference (blue)

#### 4.2 Other influencing factors

#### **Residual magnetization**

Residual magnetization is a frequently occurring phenomenon caused by previous measurements, such as a DC winding resistance measurement. This can be avoided by demagnetization before performing SFRA

tests. The influence reveals, in particular, in the very low-frequency range as shown in Figure 13 where the core resonance is shifted to the right. The other parts of the SFRA trace are unaffected by this phenomenon. Therefore, residual magnetism can be simply identified and usually does not influence further analysis.

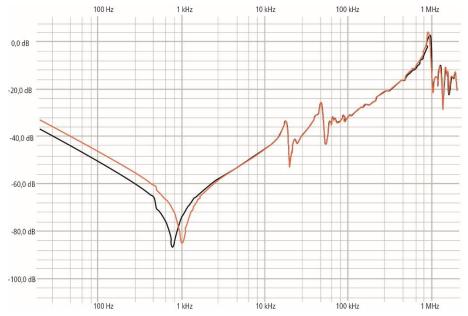


Figure 13: Frequency response of a power transformer measured in an open-circuit test before (red) and after (black) demagnetization

#### **Insulating fluid**

A power transformer should always be measured with the same configuration as it will be on site. This includes the insulation fluid, as it significantly influences the frequency response. When comparing SFRA measurements of an unfilled and oil-filled power transformer, as shown in Figure 14, a systematic shift of characteristic frequencies can be observed. This is caused by the different dielectrics (air/gas with  $\varepsilon_{r,gas} = 1$  vs. oil with  $\varepsilon_{r,oil} = 2,2$ ) and roughly corresponds to the theoretical value which can be calculated by the square root of the relative permittivity of mineral oil [11].

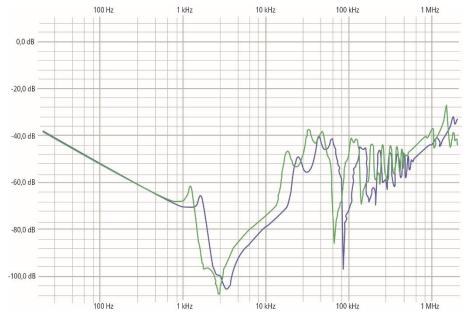


Figure 14: Measured HV traces with oil filled (green) and unfilled (blue) tank

### Temperature

Ambient environmental conditions, such as temperature, can influence the measured frequency responses. However, investigations have shown that the thermal coefficients for shifting the resonance points with temperature are very small [12]. As a consequence, the shift can be neglected in the typical temperature range between 15°C (59°F) and 70°C (185°F).

### Conclusion

The importance of a suitable connection technique was pointed out. The advantages of the technique suggested by IEC 60076-18 in comparison with other techniques were discussed. Besides a high degree of reproducibility, the use of ground braids instead of simple wires helps to avoid the influence of narrow-band noise around mains frequency and increases the reproducibility, especially in the high-frequency range above 500 kHz.

Influencing factors of the frequency response were named, described and examples for the change in the curve shape were given. This includes their influence on the measurement setup, such as shorting or grounding of tertiary windings, measurement direction, output voltage, connection technique or tap changer position. Besides this, other effects were discussed, such as residual magnetization, the influence of insulation fluid or changes due to temperature and humidity.

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### **Biographies**



**Michael Rädler** holds a Dipl. Ing. (FH) degree in industrial engineering from the University of Applied Science in Mittweida, Germany. After graduating from the HTL (Federal Secondary College of Engineering) in Bregenz, Austria, in 2007, he started his professional career as an application engineer at OMICRON electronics, where he focused on power transformers. Since September 2013 he has been the product manager for OMICRON's multifunctional primary test system for substation commissioning and maintenance (CPC 100). He has published several papers about electrical measurements on power transformers, is a member of Cigre and is part of the SFRA working group.



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